**Sprint Planning Meeting Minutes: May 26th, 2017**

For Sprint 1

Attendees: Hamilton Chevez, Bernardo Pla, Daniel Khawand, Daniel Rivero, Pachev Joseph

Start time: 19:30

End time: 20:15

After discussion, the velocity of the team were estimated to be 142

The product owner chose the following user stories to be done during the next sprint. They are ordered based on their priority.

* #719 Level 1 -24 pts
* #692 Design Connection For Mouse - 16 pts
* #721 Add Connection interface for USB Mouse- 8 pts
* #696 Setup Servo Browser- 18 points
* #681 Create Selection Sort Algorithm - 8 pts
* #691 Create Stack Interface Scene - 10 pts
* #687 WebVR Scene User Movement - 8 pts
* #690 Implement Queue Interface Scene - 10 pts
* #725 Implement Hash-Table Interface Scene - 10 pts
* #713 Oculus Rift Testing/Setup - 4 pts
* #722 Input device events - mouse - 16 pts
* #726 Native APIs - 10 pts

The team members indicated their willingness to work on the following user stories.

* Daniel Rivero
  + #719 Level 1
    - Very willing
* Hamilton Chevez
  + #691 Create Stack Interface Scene
    - Very WIlling
  + #681 Create Selection Sort Algorithm
    - Very Willing
* Pachev Joseph
  + #721 Add connection Interface for USB Mouse
    - Very willing
  + #692 Design Connection For Mouse
    - Very willing
  + #696 Setup Servo browser
    - Willing
* Bernardo Pla
  + #722 Input Device Events - Mouse
    - Very willing
  + #726 Native APIs
    - Very willing
  + #669 Rust Programming Language
    - Very willing
* Daniel Khawand
  + #687 WebVR Scene User Movement
    - Very Willing
  + #690 Implement Queue Interface Scene
    - Very Willing
  + #713 Oculus Rift Testing/Setup
    - Very Willing
  + #725 Implement Hash-Table Interface Scene
    - Willing

**Sprint Planning Meeting Minutes: June 11, 2017**

For Sprint 2

Attendees: Hamilton Chevez, Bernardo Pla, Daniel Khawand, Daniel Rivero, Pachev Joseph

Start time: 17:15

End time: 18:45

After discussion, the velocity of the team was estimated to be 94% or 134 points. For this coming sprint, we expect to accomplish 200 points, for an average expected velocity of 167 points.

The product owner chose the following user stories to be done during the next sprint. They are ordered based on their priority.

* #752 Video Game Controller- 24 pts
* #754 Touch input - 24pts
* #758 Generic Empty Device Implementation - 24 pts
* #762 Touch Device Implementation - 24 pts
* #765 Design Website Theme - 4pts
* #762 Selenium Testing Tool - 4 pts
* #684 Binary Search Tree Scene - 12 pts
* #637 [Bot Design] Module Collision- 24 pts
* #675 Robot Controller -24 pts
* #690 Queue Interface Scene - 4 pts
* #725 Implement Hash-Table Interface Scene - 4 pts
* #767 Dynamic Stack Interface Scene - 24 pts
* #768 Visualization Research - 4 pts
* Pachev Joseph
  + #752 Video Game Controller
    - Very willing
  + #754 Touch Input
    - Very willing
* Bernardo Pla
  + #758 Generic Empty Device Implementation
    - Very willing
  + #763 Touch Device Implementation
    - Very willing
* Daniel Rivero
  + #675 Robot Controller
    - Very Willing
  + #637 [Bot Design] Module Collision
    - Very Willing
* Hamiton Chevez
  + #684 Binary Search Tree Scene
    - Very Willing
  + #762 Selenium Testing Tool
    - Very Willing
  + #765 Website Design Theme
    - Very Willing
* Daniel Khawand
  + #690 Implement Queue Interface Scene
    - Very Willing
  + #767 Dynamic Stack Interface Scene
    - Very Willing
  + #725 Implement Hash-Table Interface Scene
    - Very Willing

**Sprint Planning Meeting Minutes: June 25, 2017**

For Sprint 3

Attendees: Hamilton Chevez, Pachev Joseph, Bernardo Pla, Daniel Rivero, Daniel Khawand

Start time: 10:30 PM

End time: 11:30 PM

After discussion, the velocity of the team was estimated to be 100% or Z points. For this coming sprint, we expect to accomplish A points, for an average expected velocity of B points.

The product owner chose the following user stories to be done during the next sprint. They are ordered based on their priority.

* #684 Binary Search Tree Scene - 12 points
* #679 Merge Sort Scene - 8 Points
* #754 Touch input - 24pts
* #696 Setup Servo Browser- 24pts
* #777 Web Application for Implemented Devices - 24pts
* #778 Integrate Web Application with Servo Browser - 24pts
* #779 WebGL Demo Function Implementation - 24 pts
* #780 Research on WebVR - 8 pts
* #676 Transition Visualization & Logic -24pts
* #720 Complete realization of level 1 - 24pts
* Pachev Joseph
  + #754 Touch Input
    - Very Willing
  + # 696 Setup Servo Browser
    - Very Willing
* Bernardo Pla
  + #777 Web Application for Implemented Devices
    - Very Willing
  + #778 Integrate Web Application with Servo Browser
    - Very Willing
* Daniel Rivero
  + #676 Transition Visualization & Logic
    - Very Willing
  + #720 Complete realization of level 1
    - Very Willing
* Hamiton Chevez
  + #684 Binary Search Tree Scene
    - Very Willing
  + #679 Merge Sort Scene
    - Very WIlling
* Daniel Khawand
  + #779 WebGL Demo Function Implementation
    - Very Willing
  + #780 Research on WebVR
    - Very Willing

**Sprint Planning Meeting Minutes: July 8th, 2017**

For Sprint 4

Attendees: Hamilton Chevez, Pachev Joseph, Bernardo Pla, Daniel Rivero, Daniel Khawand

Start time: 4:10 PM

End time: 5:00 PM

After discussion, the velocity of the team was estimated to be 100% or Z points. For this coming sprint, we expect to accomplish A points, for an average expected velocity of B points.

The product owner chose the following user stories to be done during the next sprint. They are ordered based on their priority.

* #783 Debug Device Library for Implemented Devices - 24 pts
* #784 VIP Documentation - 24 pts
* #785 VIP Documentation - 12pts
* #787 Debug WebVR Scene Usage - 10 pts
* #786 Research Documentation - 12 pts
* #674 Robot Inventory - 16pts
* #677 User Inventory - 16pts
* #788 Selection Sort Using WebVR API - 24 pts
* #789 VIP Final Documenation - 12 pts
* #696 Setup Servo Browser for Testing
* Pachev Joseph
  + #696 Setup Servo Browser
    - Very Willing
* Bernardo Pla
  + #783 Debug Device Library for Implemented Devices
    - Very Willing
  + #784 VIP Documentation
    - Very Willing
* Daniel Rivero
  + #674 Robot Inventory
    - Very Willing
  + #677 User Inventory
    - Very Willing
* Hamiton Chevez
  + #785 VIP Documentation
    - Very Willing
  + #787 Debug WebVR Scene Usage
    - Very Willing
  + #786 Research Documentation
    - Very Willing
* Daniel Khawand
  + #788 Selection Sort Using WebVR Api
    - Very Willing
  + #789 VIP Final Documentation
    - Very Willing